

---

# Coarsening

---

**Leticia F. Cugliandolo**

LPTHE Jussieu & LPT ENS, Paris France – IUF

`leticia@lpt.ens.fr`

with

J. J. Arenzon (Porto Alegre), A. J. Bray (Manchester) & A. Sicilia (Paris),  
cond-mat/0608270.

**Buenos Aires, 12/10/2006**

---

# Plan

---

1. Review of Coarsening phenomena

ex. ferromagnetic systems.

2. The scaling hypothesis.

Analytical and numerical results.

3. New : details on the domain conformations.

Analytical and numerical results.

4. Work in progress.

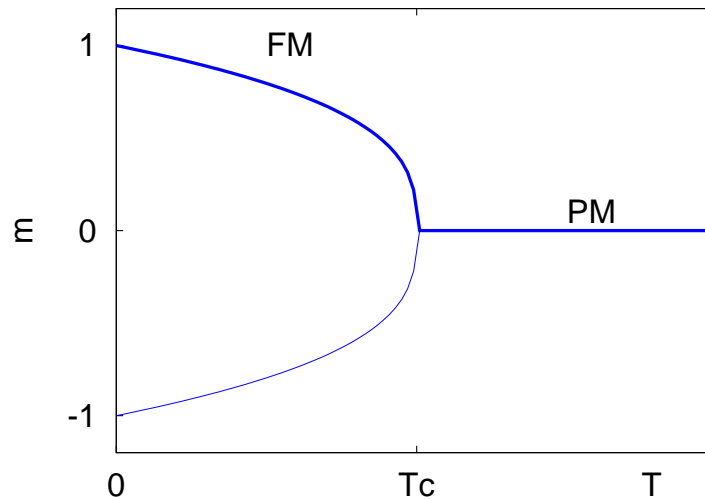
5. Why should one look at this problem ?

---

# Ferromagnets in equilibrium

---

A ferromagnetic system in contact with a heat bath at temperature  $T$  under no applied field ( $h = 0$ ) acquires a magnetization density  $m$  below a critical temperature  $T_c$  :



$m$  is the order parameter.

**Curie-Weiss mean-field theory (1907), Ginzburg-Landau theory (1937, 1950),  
Wilson renormalization group (1971).**

---

# The standard Ising model

---

$$H = -J \sum_{\langle ij \rangle} s_i s_j , \quad \text{Ising, 1925}$$

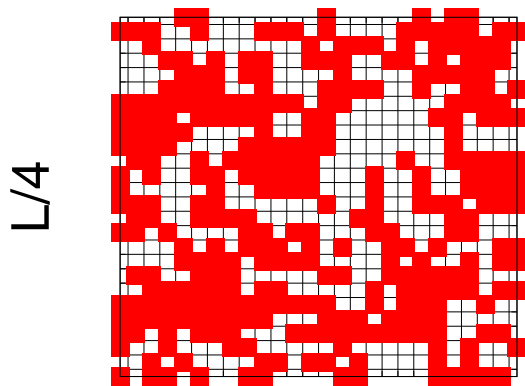
- The spins  $s_i$  take bimodal values,  $s_i = \pm 1$ .
- The sum  $\sum_{\langle ij \rangle}$  runs over nearest neighbours on a  $d$  dimensional, typically hypercubic, lattice.
- $J > 0$  is the coupling strength.

One finds

$$\frac{T_c}{J} \begin{cases} = 0 , & d = 1 & \text{exact (Ising, 1925),} \\ \sim 2.27 , & d = 2 & \text{exact (Onsager, 1944),} \\ \sim 4.5 , & d = 3 & \text{num. (D. P. Landau, 1976).} \end{cases}$$

# Equilibrium configurations

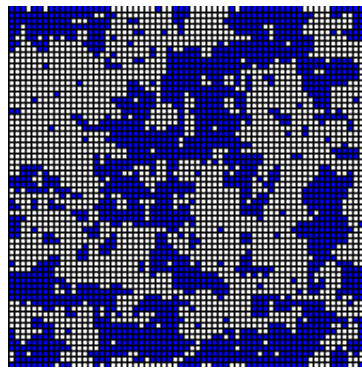
*2d* slices of a *3d* Ising model



$$T \rightarrow \infty$$

Random configuration

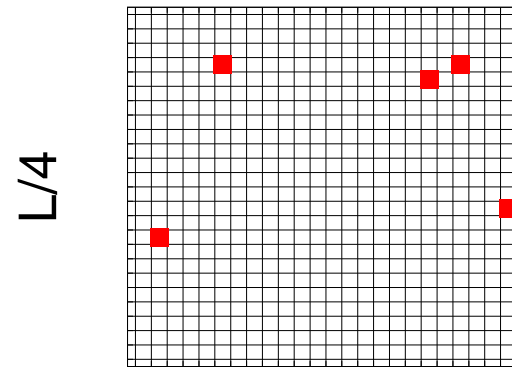
$$s_i = \pm 1$$



$$T \sim T_c$$

Structures of all sizes

Self-similarity



$$T < T_c$$

Essentially ordered

Thermal fluct. ( $m < 1$ )

---

# Ginzburg-Landau

---

Coarse-graining  $\Rightarrow$  the local magnetization density

$$\phi(\vec{x}) = \frac{1}{\ell^d} \sum_{i \in V_{\vec{x}, \ell}} s_i, \quad Z = \sum_{\phi} e^{-\beta F(\phi)}.$$

Symmetry arguments ( $\phi \rightarrow -\phi$ ) and  $\langle \phi \rangle \sim 0$  at  $T \sim T_c$  suggest

$$F(\phi) = \int d^d x \left[ \underbrace{\frac{c}{2} (\nabla \phi)^2}_{\text{Energy-cost domain-wall}} + \underbrace{\frac{T - T_c}{T_c} \phi^2 + \frac{\lambda}{4} \phi^4}_{\text{Symmetric double-well}} \right]$$

Energy-cost  
domain-wall

Symmetric  
double-well

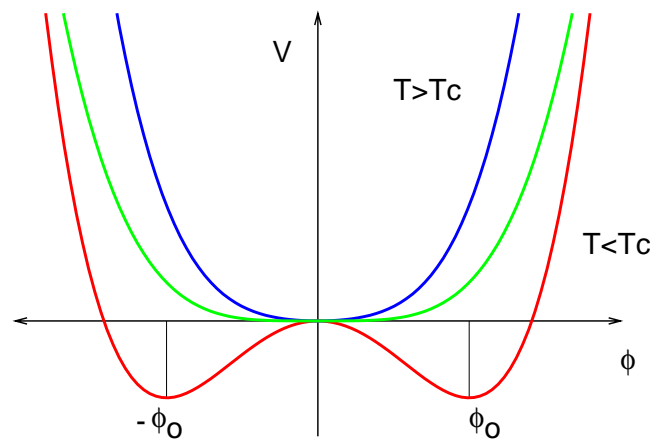
---

# Ginzburg-Landau

---

Large volume limit

$F \approx L^d \Rightarrow$  saddle-point, mean-field or stationary phase approx.

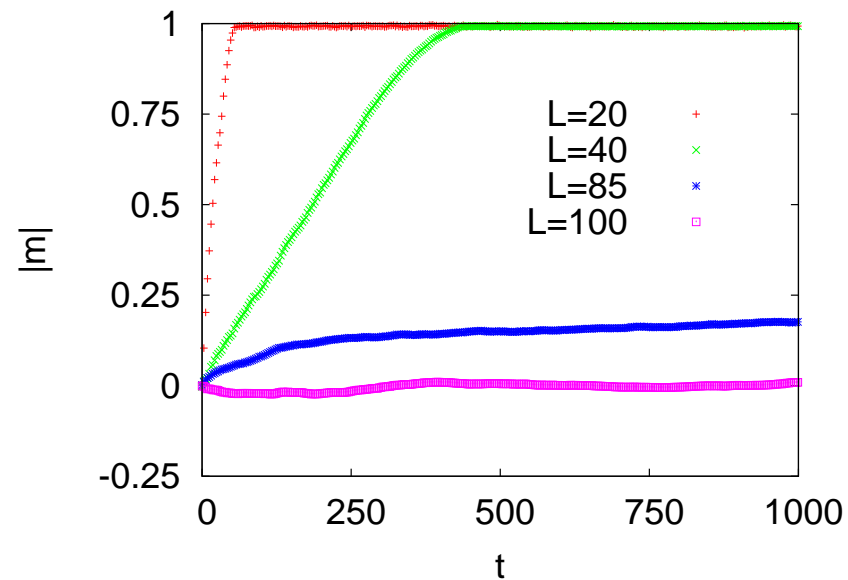
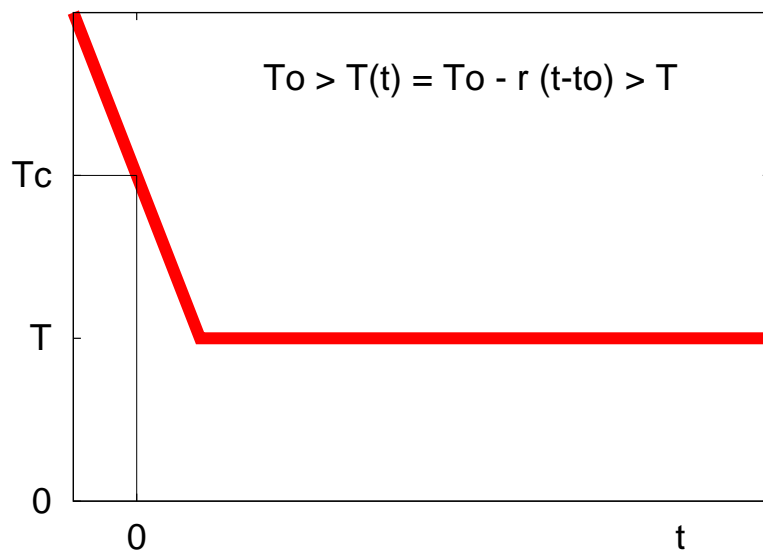


$$\langle \phi(\vec{x}) \rangle = \phi_o \propto (T_c - T)^{\frac{1}{2}} , \quad \beta = \frac{1}{2} .$$

Essentially correct but for the critical region (e.g.  $\beta \sim 1/3$ ).

# Evolution

A rapid quench



Stochastic dynamics ; Monte Carlo updates

Note : the order parameter ( $m$ ) is not conserved.

Slow dynamics

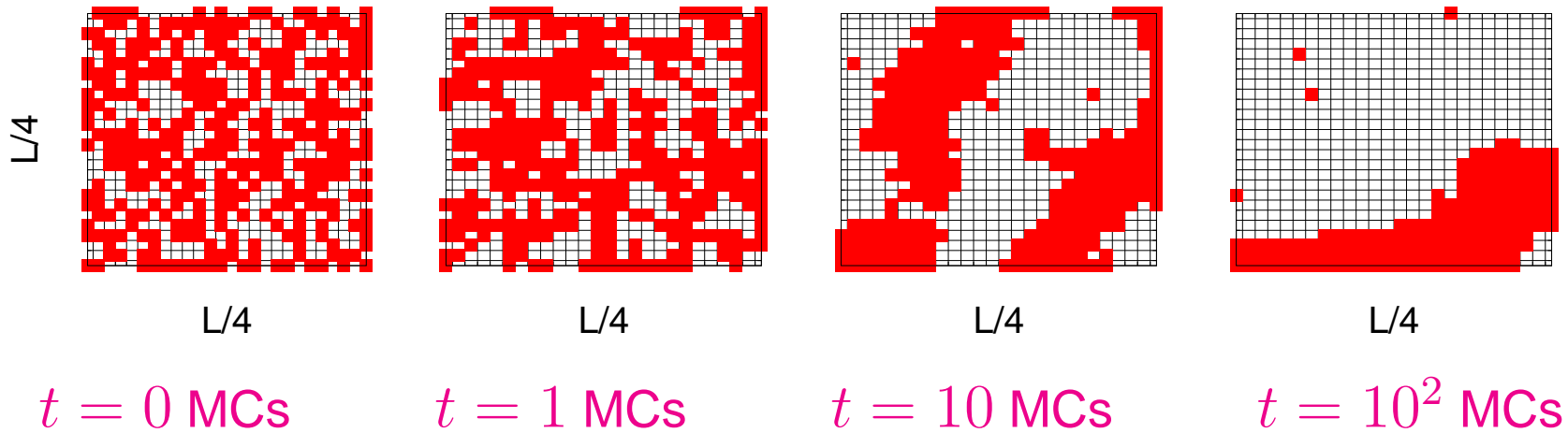


---

# Domain growth

---

After a rapid quench



---

# Time-dep. Ginzburg-Landau

---

$$\phi(\vec{x}) \rightarrow \phi(\vec{x}, t) = \frac{1}{\ell^d} \sum_{i \in V_{\vec{x}, \ell}} s_i(t)$$

Langevin dynamics in  $F(\phi)$ , model A (Hohenberg & Halperin 1977).

$$\begin{aligned} \gamma \frac{\partial \phi(\vec{x}, t)}{\partial t} &= - \frac{\delta F(\phi)}{\delta \phi(\vec{x}, t)} + \eta(\vec{x}, t) \\ &= \nabla^2 \phi(\vec{x}, t) + a\phi(\vec{x}, t) - \lambda\phi^3(\vec{x}, t) + \eta(\vec{x}, t) , \end{aligned}$$

with  $\gamma = t_0^{-1}$  and  $\eta$  a Gaussian white noise,

$$\langle \eta \rangle = 0 \text{ and } \langle \eta(\vec{x}, t) \eta(\vec{x}', t') \rangle = 2k_B T \gamma \delta(\vec{x} - \vec{x}') \delta(t - t').$$

---

# Scaling theory

---

At late times there is a single *length-scale*, the *typical radius of the domains*  $R(T, t)$ , such that the domain structure is (in statistical sense) independent of time when lengths are scaled by  $R(T, t)$ , e.g.

$$C(r, t) \equiv \langle s_i(t) s_j(t) \rangle_{|\vec{x}_i - \vec{x}_j| = r} \sim m_{eq}^2(T) f\left(\frac{r}{R(T, t)}\right),$$

$$C(t, t_w) \equiv \langle s_i(t) s_i(t_w) \rangle \sim m_{eq}^2(T) g\left(\frac{R(T, t)}{R(T, t_w)}\right),$$

etc. when  $r \gg \xi(T)$ ,  $t, t_w \gg t_0$  and  $C < m_{eq}^2(T)$ .

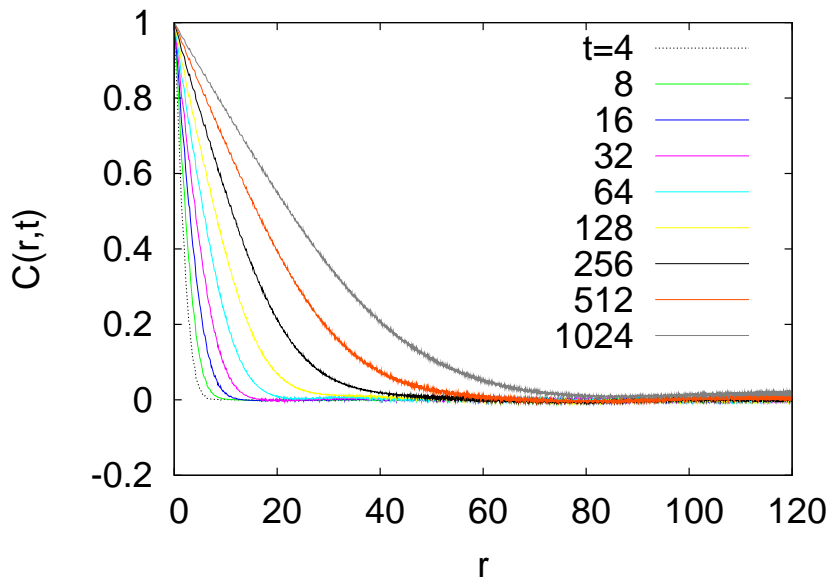
Suggested by experiments and numerical simulations. Proven in

- Ising chain with Glauber dynamics.
- Langevin dynamics of the  $O(N)$  model with  $N \rightarrow \infty$ , and the spherical ferromagnet.

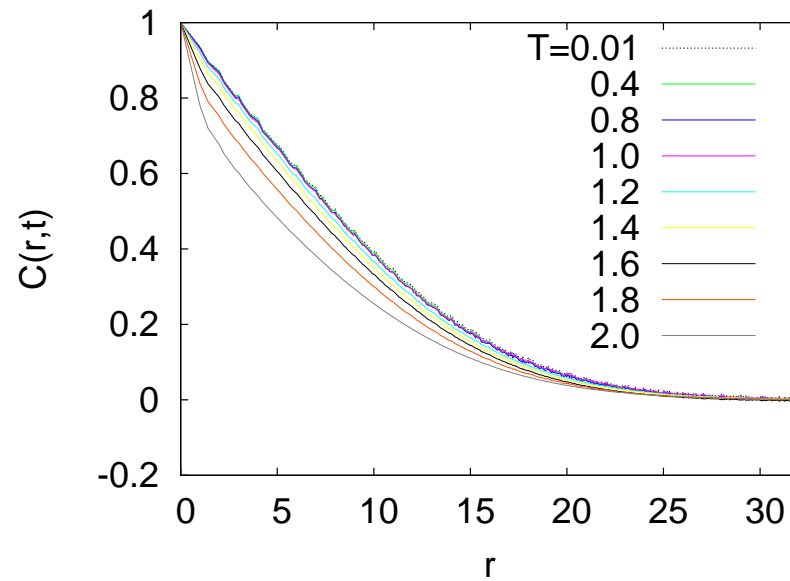
**Review A. J. Bray, 1994.**

# MC dynamics 2dIM

Equal-times spatial correlation



$T = 0.5$

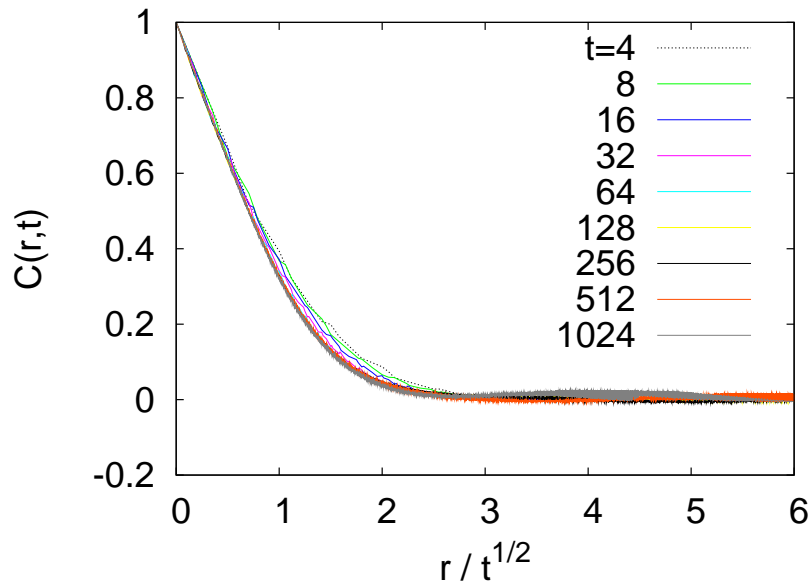


$t = 128$  MCs

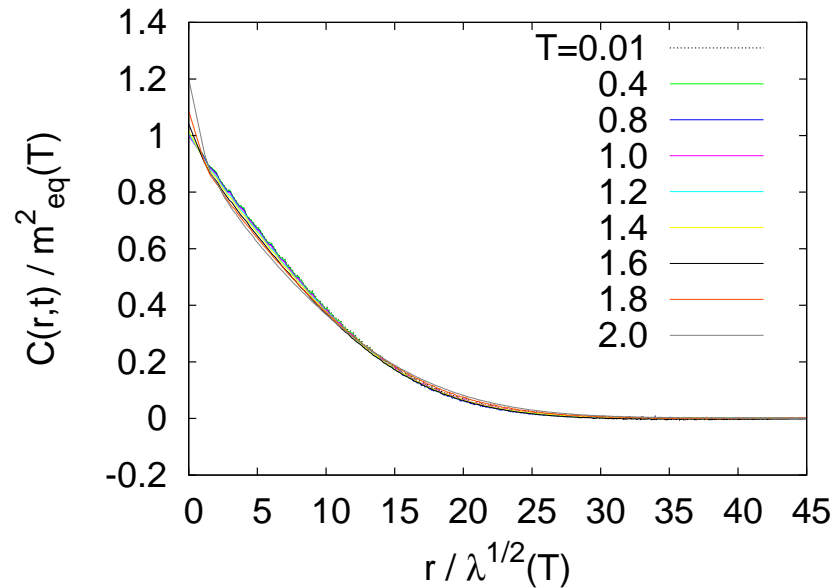
$$C(r, t) \equiv \langle s_i(t) s_j(t) \rangle |_{|\vec{x}_i - \vec{x}_j| = r} \sim m_{eq}^2(T) f\left(\frac{r}{R(T, t)}\right)$$

# MC dynamics 2dIM

Equal-times spatial correlation : scaling



$T = 0.5$



$t = 128$  MCs

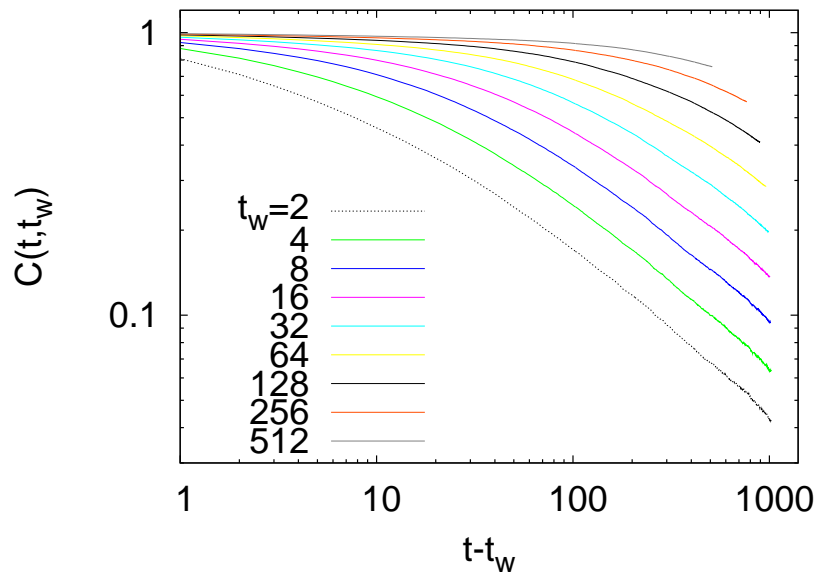
$$C(r, t) \sim m_{eq}^2(T) f\left(\frac{r}{R(T, t)}\right)$$

with

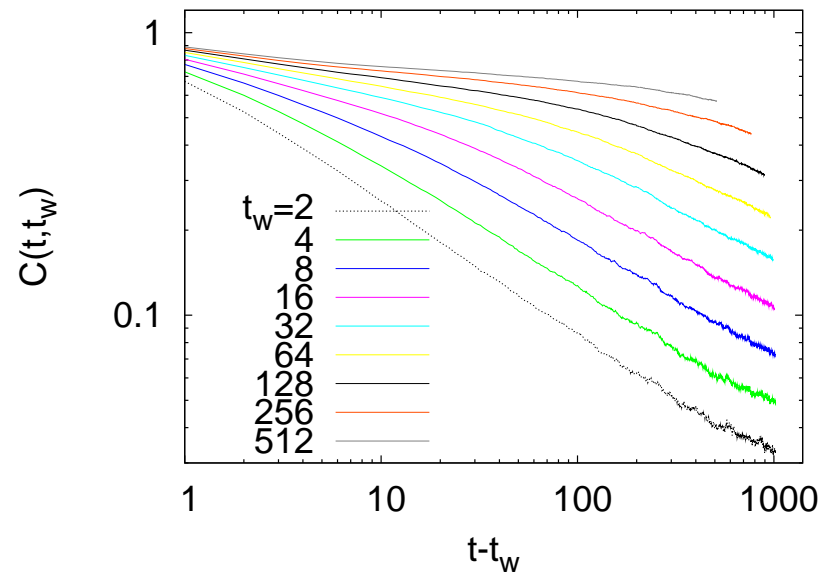
$$R(T, t) \sim [\lambda(T)t]^{1/2}$$

# MC dynamics 2dIM

## Two-times local correlation



$T = 0.5$

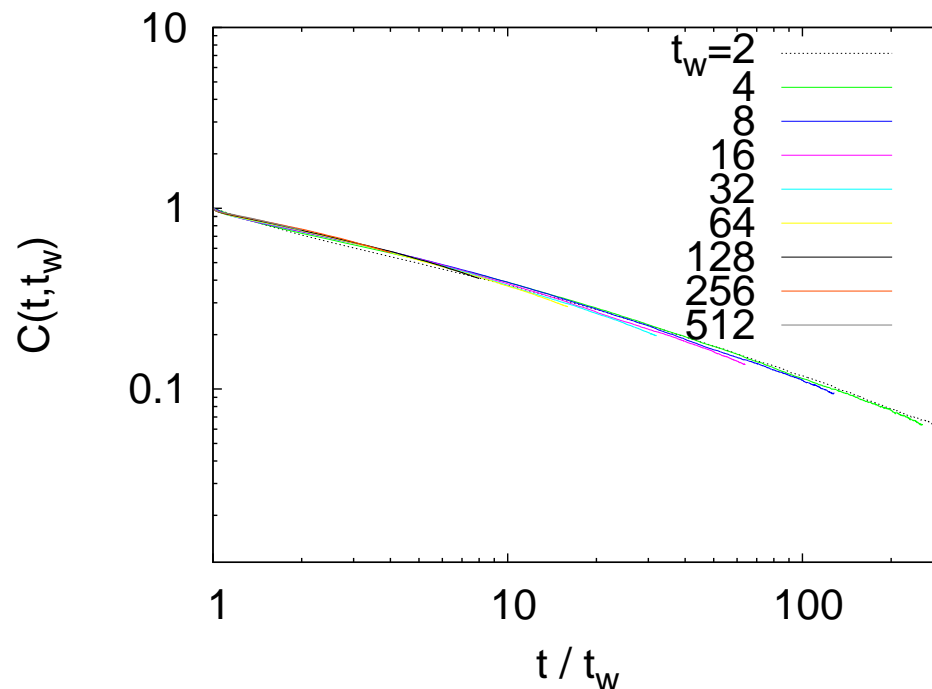


$T = 2$

$$C(t, t_w) = N^{-1} \sum_{i=1}^N \langle s_i(t) s_i(t_w) \rangle \sim m_{eq}^2(T) g \left( \frac{R(T, t)}{R(T, t_w)} \right)$$

# MC dynamics 2dIM

Two-times local correlation



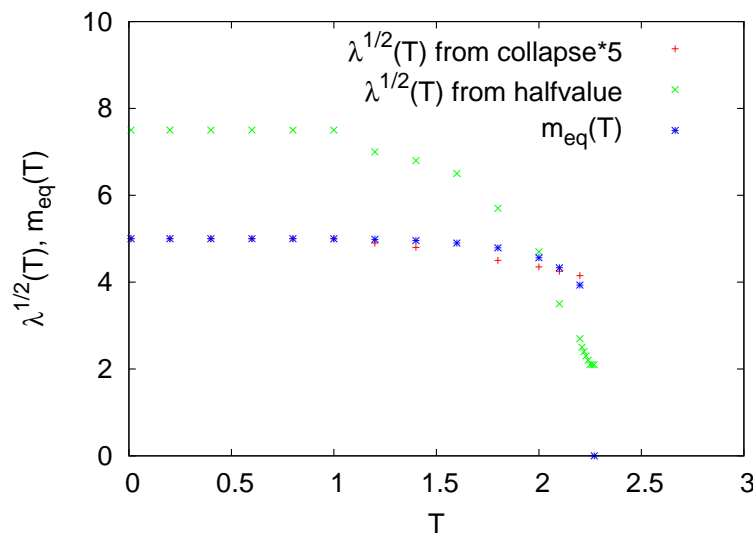
$$T = 0.5$$

$$C(t, t_w) \sim m_{eq}^2(T) \, g\left(\frac{R(T, t)}{R(T, t_w)}\right) \quad \text{for} \quad C < m_{eq}^2(T) \sim 1$$

# MC dynamics 2dIM

The typical length-scale  $\Leftrightarrow$  a typical area

$$R(T, t) \sim \sqrt{\lambda(T) t} \quad \Leftrightarrow \quad A(T, t) \sim \lambda(T) t$$



NB the exponent  $\frac{1}{2}$  is independent of  $T$  and the details of the dynamics, lattice, *etc.* as long as the order parameter is non-conserved.

The  $T$ -dependence in  $\lambda(T)$  is due to the roughening of the domain walls.



---

# Fluctuations

---

What happens locally ?

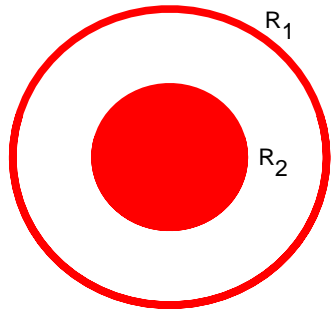
Basic question : what does  $R$  really mean ?

- How many domains ?
- Which sizes ?

---

# Domains and hulls

---



Two hulls

$$A_1 = \pi R_1^2$$

$$A_2 = \pi R_2^2$$

Two domains

$$A_1 = \pi(R_1^2 - R_2^2)$$

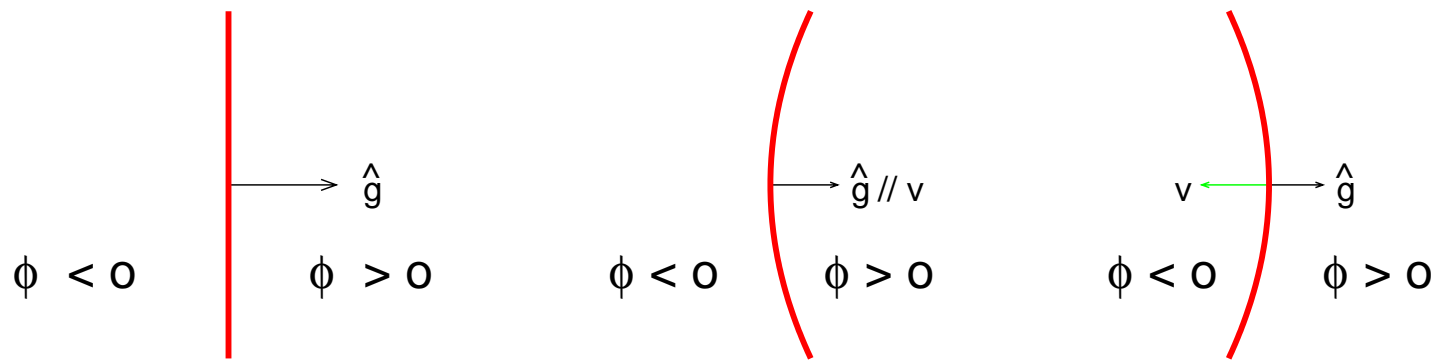
$$A_2 = \pi R_2^2$$

*Hull : the interior of a domain boundary.*

- Typically hulls tend to be larger than domains ( $A_1^h > A_2^h$ ).
- There are as many hulls as domains (two).
- Each spin belongs to one and only one domain (e.g. spin at the center).
- A spin can belong to more than one hull (e.g. spin at the center).

# Velocity of a quasi-planar wall

Time-dependent Ginzburg-Landau



$$v = -\vec{\nabla} \cdot \hat{g} = -K$$

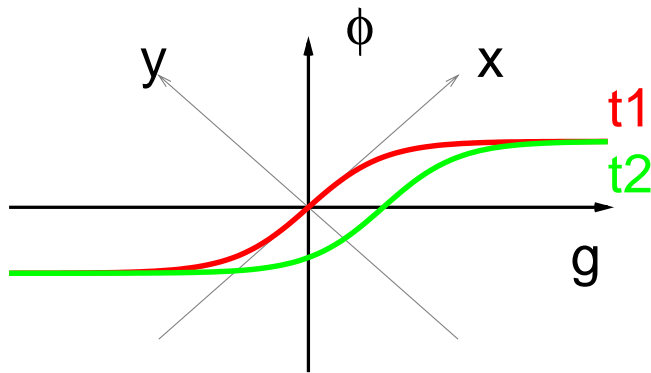
where  $\hat{g}$  points in the direction  $\phi > 0$  and

$K$  is the mean curvature measured from the phase  $\phi < 0$ .

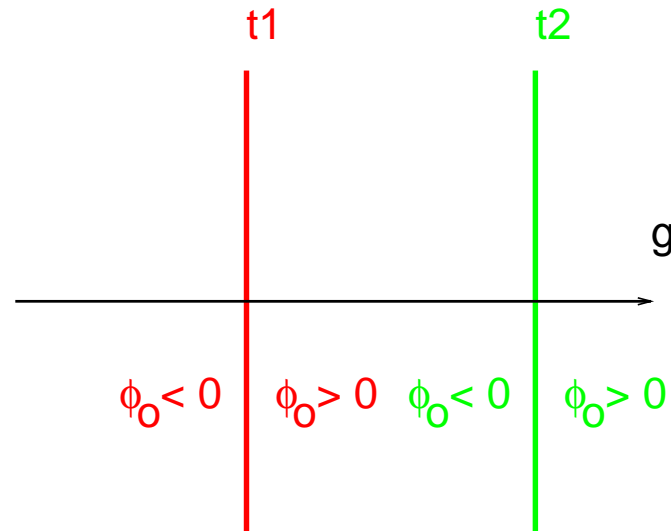
**S. M. Allen & J. W. Cahn, Acta Metall. 27, 1085 (1979).**

# T=0 argument

Domain wall profile



View from the top



$$\frac{\partial \phi(\vec{x}, t)}{\partial t} = - \left. \frac{\partial \phi(\vec{x}, t)}{\partial g} \right|_t \left. \frac{\partial g}{\partial t} \right|_\phi, \quad \vec{\nabla} \phi(\vec{x}, t) = \left. \frac{\partial \phi(\vec{x}, t)}{\partial g} \right|_t \hat{g},$$

$$\nabla^2 \phi(\vec{x}, t) = \left. \frac{\partial^2 \phi(\vec{x}, t)}{\partial g^2} \right|_t + \left. \frac{\partial \phi(\vec{x}, t)}{\partial g} \right|_t \vec{\nabla} \cdot \hat{g}.$$

Using  $\left. \frac{\partial^2 \phi(\vec{x}, t)}{\partial g^2} \right|_t = V'(\phi)$  in the GL equation:  $v \equiv \partial_t g|_\phi = -\vec{\nabla} \cdot \hat{g}$ .

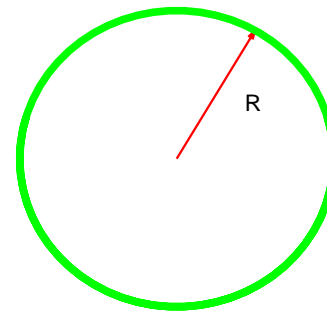
---

# Proof II

---

A spherical hull in  $d = 2$

Take a sphere with radius  $R$ ,  
area  $A = \pi R^2$  and perimeter  
 $L = 2\pi R$ .



The time-variation of the *hull area*,  $\frac{dA}{dt} = 2\pi R \frac{dR}{dt} = L v$ , in  
the case  $v = -\frac{\lambda}{2\pi} \kappa$ , with the curvature  $\kappa = \frac{1}{R}$ , is just constant

$$\frac{dA}{dt} = -\lambda$$

---

# Proof III

---

A generic hull in  $d = 2$

with radius  $R$ , area  $A$  and  
perimeter  $L$ .



The time-variation of the *hull area*,  $\frac{dA}{dt} = \oint \vec{v} \wedge d\vec{\ell} = \oint v d\ell$ , in  
the case  $v = -\frac{\lambda}{2\pi}\kappa$ , with  $\kappa$  the *geodesic curvature*, is also constant

$$\frac{dA}{dt} = -\lambda$$

due to the Gauss-Bonnet theorem  $\int_A K dA + \int_{\partial A} \kappa d\ell = 2\pi\chi(A)$  that  
simply becomes  $\oint \kappa d\ell = 2\pi$  for a planar  $2d$  manifold with no holes.

---

# Proof IV

---

A spherical hull in  $d = 3$

Take a sphere with radius  $R$ , volume  $V = \frac{4}{3}\pi R^3$  and surface  $A = 4\pi R^2$ .

The time variation of the *hull* volume,  $\frac{dV}{dt} = 4\pi R^2 \frac{dR}{dt}$ , in the case  $v = -\frac{\lambda}{2\pi}\kappa$ , with  $\kappa$  the *mean* curvature, *is not* constant :

$$\frac{dV}{dt} = -2R \propto -V^{1/3} .$$

Guess :  $\frac{dV}{dt} \sim -V^{1/3}$  for generic geometries.

---

# The hull area distribution

---

$$d = 2$$

$\frac{dA}{dt} = -\lambda \Rightarrow$  all hulls tend to disappear at the same speed  $-\lambda$ .

- hulls with initial area smaller than  $\lambda t$  will have disappeared at  $t$ .
- hulls with initial area larger than  $\lambda t$  will have decreased by  $\lambda t$ .

The full hull area distribution is advected uniformly to the left at rate  $\lambda$ .

The number of hulls, per unit area of the system, with area greater than  $A$  satisfies

$$N_h(A, t) = N_h(A + \lambda t, 0) .$$



---

# The hull area distribution II

---

## The initial condition

- Quench from an infinite temperature  $\Leftrightarrow$  random initial condition,

$s_i = \pm 1$  with  $p = \frac{1}{2}$  : critical point of percolation in  $d = 2$ .

$$N(A, 0) \approx \frac{2c}{A} \quad \text{with} \quad c = \frac{1}{8\pi\sqrt{3}} \quad (a^2 \ll A \ll L) .$$

- Quench from equilibrium at  $T_c$  : Ising cluster hulls at criticality.

$$N(A, 0) \approx \frac{c}{A} \quad \text{with} \quad c = \frac{1}{8\pi\sqrt{3}} \quad (a^2 \ll A \ll L) .$$

Conformal field theory, scaling & numerical checks

**J. Cardy and R. M. Ziff, J. Stat. Phys. 110, 1 (2003).**

---

# The prediction

---

$$N_h(A, t) = \frac{2c}{A + \lambda t} , \quad n_h(A, t) \equiv -\frac{\partial N_h(A, t)}{\partial A} = \frac{2c}{(A + \lambda t)^2} ,$$

with the expected scaling forms

$$N_h(A, t) = (\lambda t)^{-1} f(A/\lambda t) , \quad n_h(A, t) = (\lambda t)^{-2} f'(A/\lambda t) .$$

---

# Numerical simulations

---

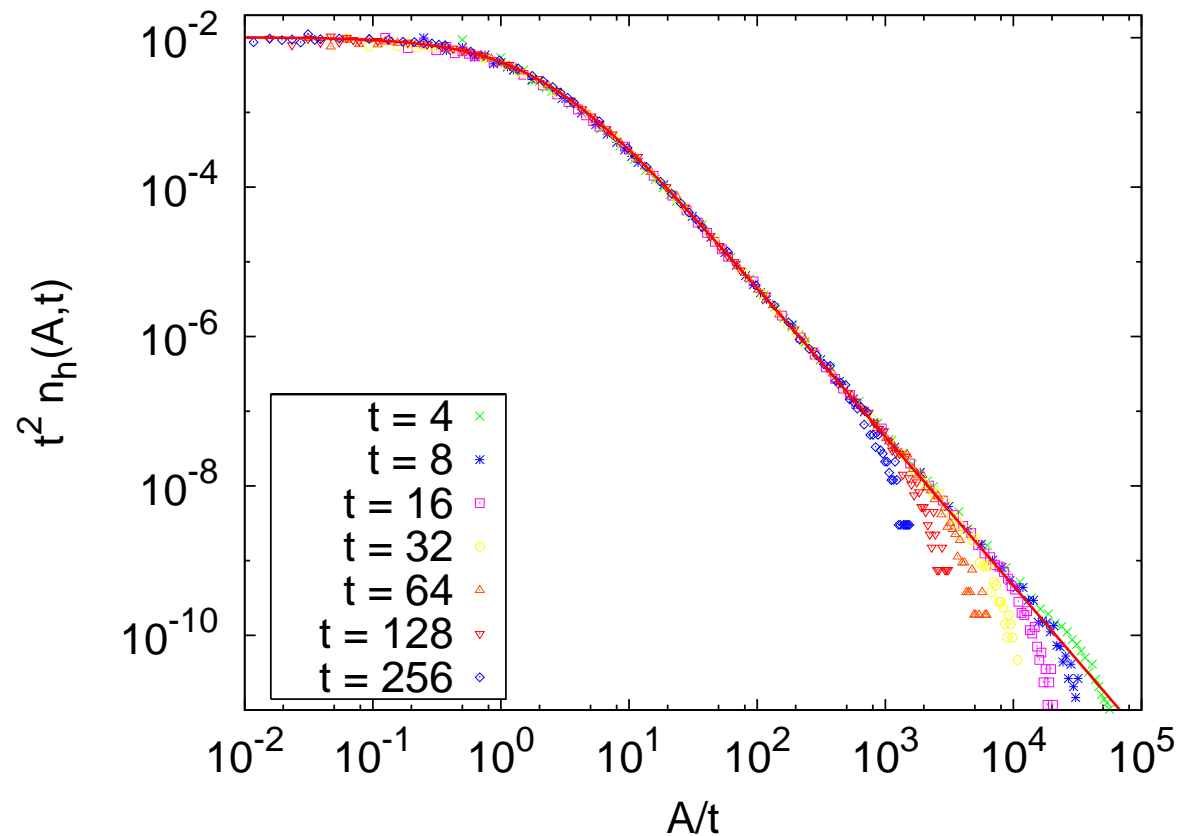
- $2d$  Ising model on a square lattice with periodic boundary conditions.
- Monte Carlo (MC) dynamics with heat-bath updates.
- $L = 10^3, 2 \times 10^3$  samples, one time step corresponds to a MC sweep.
- Critical initial conditions generated with the Swendsen-Wang cluster algorithm to avoid critical slowing down.
- Hoshen-Kopelman algorithm to identify the domains.
- Our algorithm to identify the hulls inspired by the one used in

**R. M. Ziff, cond-mat/0510633, StatPhys22..**

# Numerical tests

Number density of (finite) *hulls* per unit area

$T = 0$  dynamics after a quench from  $T \rightarrow \infty$



The bending is a finite size effect due to the percolating hulls.

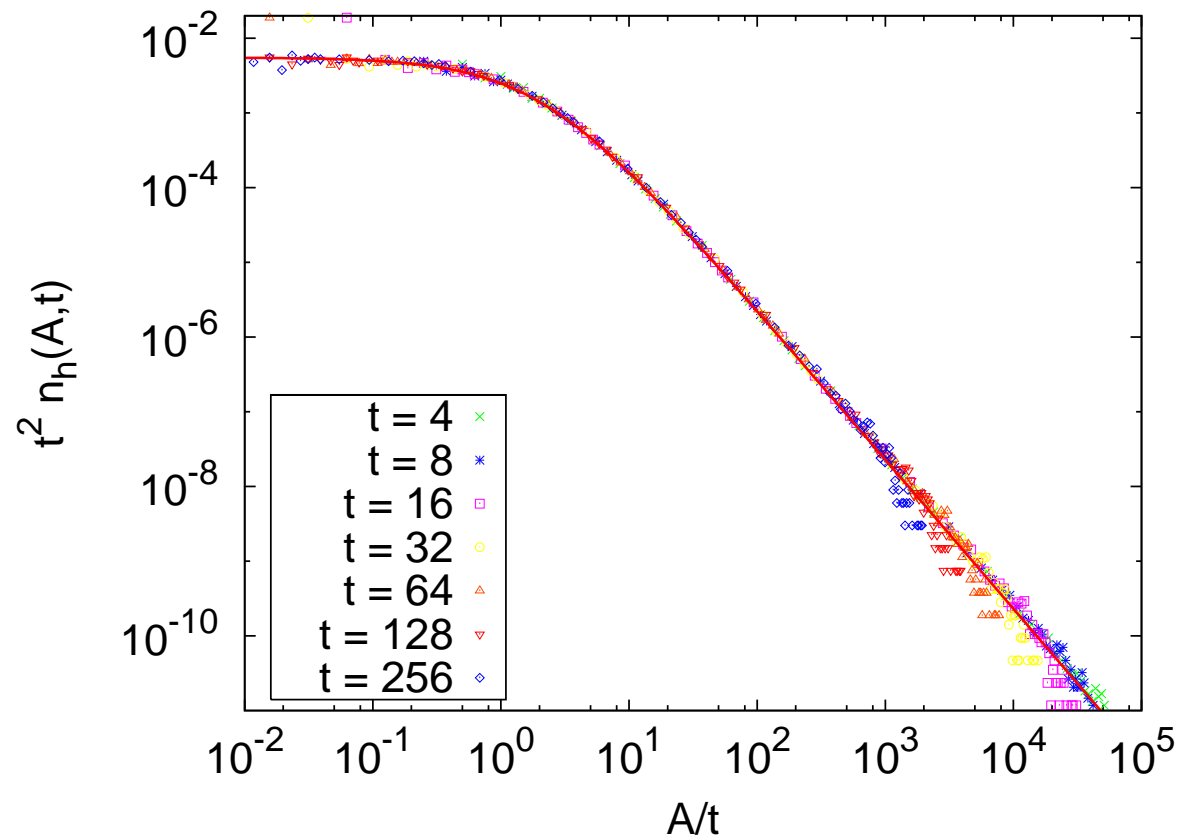
---

# Numerical results

---

Number density of (finite) *hulls* per unit area

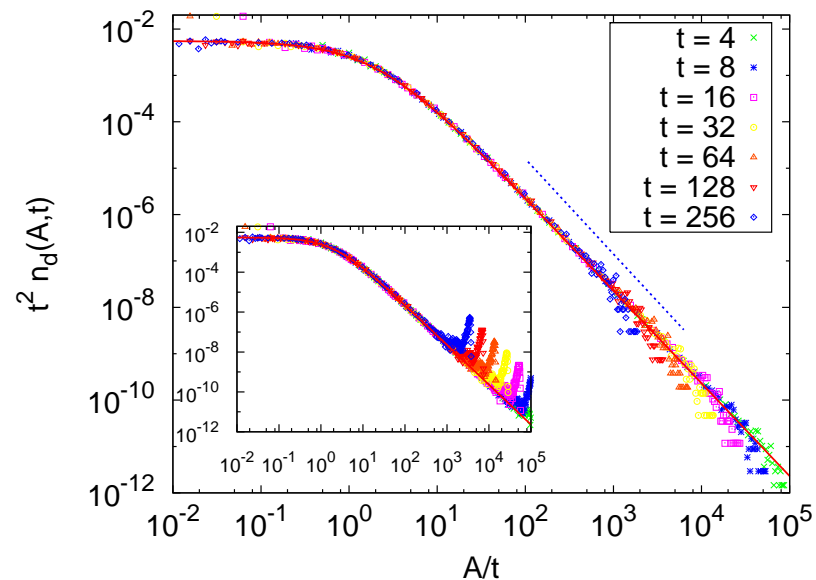
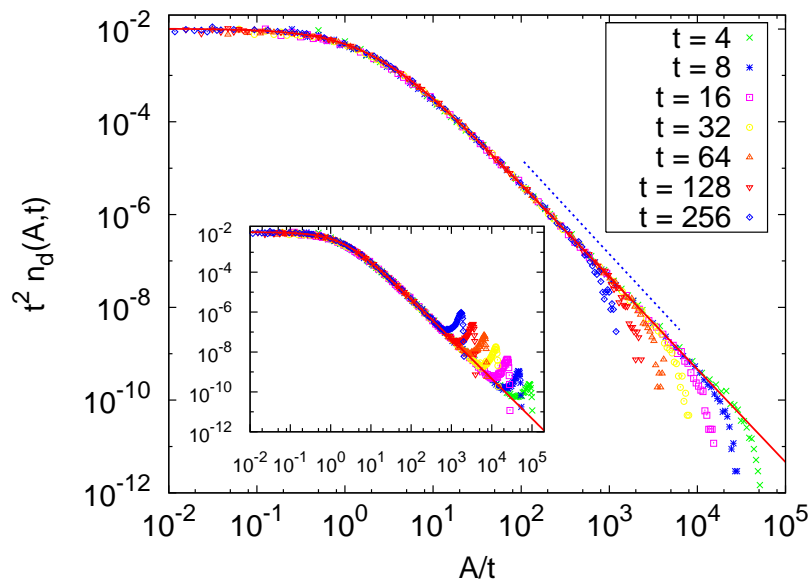
$T = 0$  dynamics after a quench from equilibrium at  $T_c$



# Numerical results

Number density of *domains* per unit area

$T = 0$  dynamics after a quench from  $T \rightarrow \infty$  (left) and  $T_c$  (right)

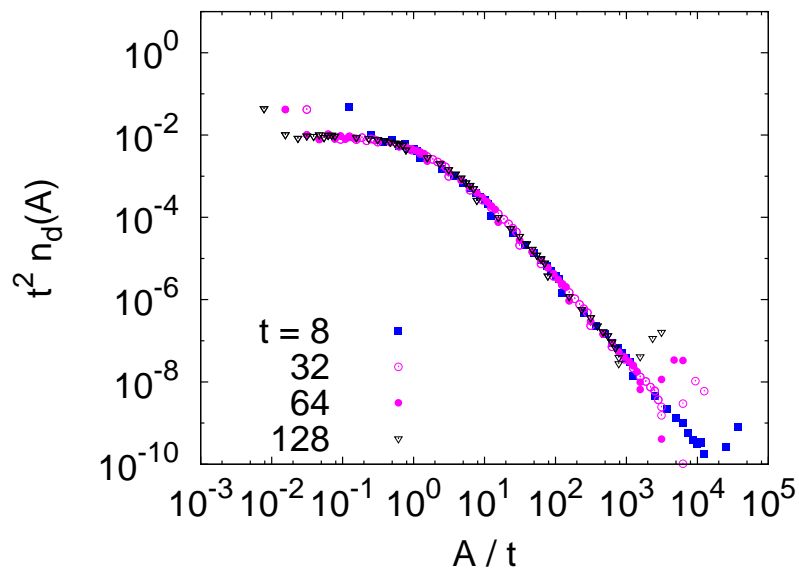


The insets include the contribution from the percolating cluster (hump).

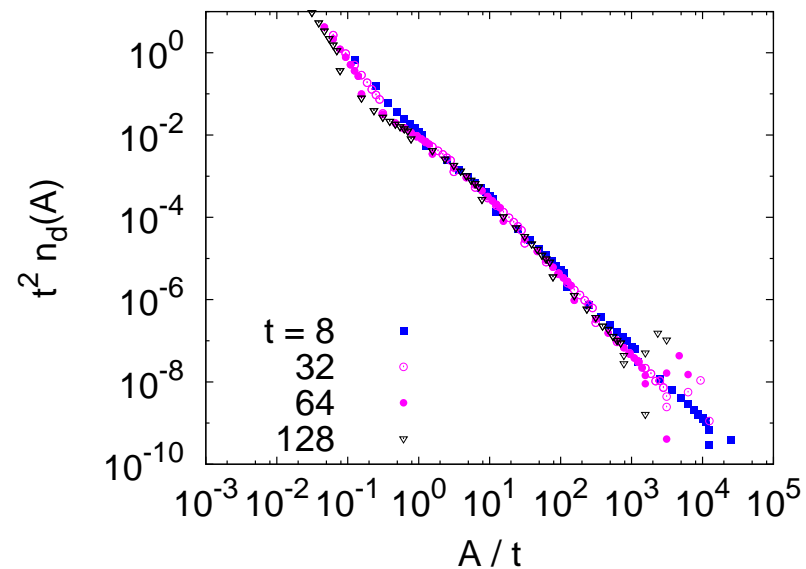
# Numerical results

Number density of domains per unit area

Finite  $T$  dynamics after a quench from  $T \rightarrow \infty$



$T = 0.5$



$T = 2$

---

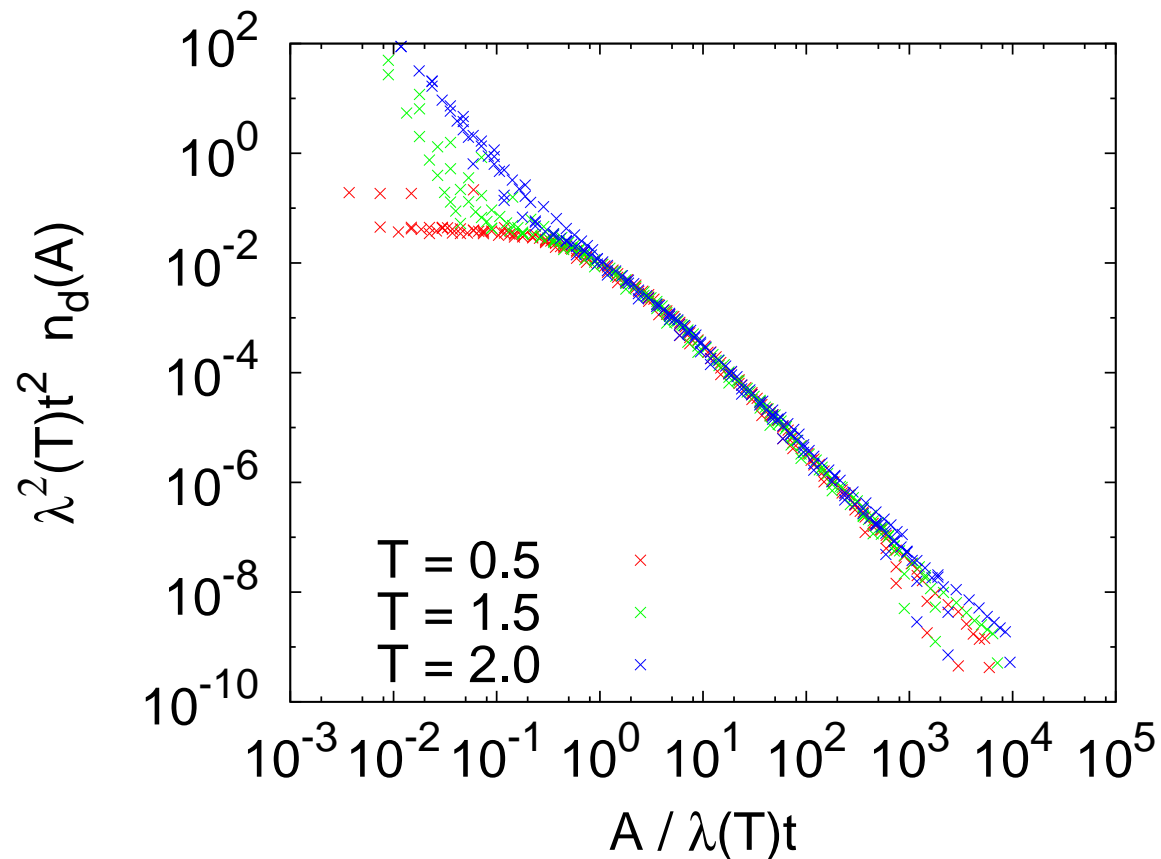
# Numerical results

---

Number density of domains per unit area

Finite  $T$  dynamics after a quench from  $T \rightarrow \infty$

Scaling



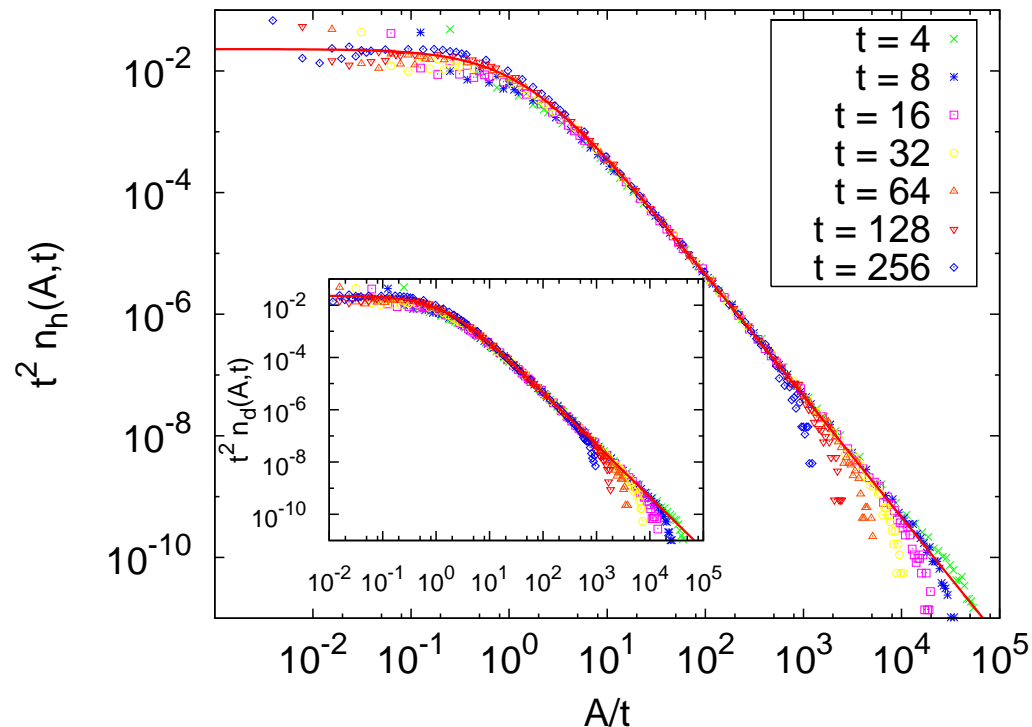


# Random ferromagnet

$$H = \sum_{\langle ij \rangle} J_{ij} s_i s_j, \quad J_{ij} \text{ uniform distributed in } [0.75, 1.25]$$

Number density of *hulls* and *domains* (inset) per unit area

$T = 0.5$  dynamics; random initial conditions



---

# Summary of results

---

- Exact results for hull pdfs.
- We proved scaling!
- The typical length-scale is not so typical after all :  
power-law tails in  $N_h$  and  $n_h$  (as well as  $N_d$  and  $n_d$ ).

---

# Future work

---

- Finite  $T$  dynamics, numerical checks.
- $3d$  Ising model.
- Conserved order parameter (model B, Kawasaki dynamics); applications to [phase separation](#).
- Potts model; application to [soap films](#) and [adsorbed atoms](#).
- Quenched randomness, *e.g. random ferromagnets, random field Ising model*; application to [hysteresis and the Barkhausen noise](#).
- Effect of annealing or finite cooling rates. Applications in [cosmology](#) : study of density of defects after a second-order phase transition.
- Understanding fluctuations in [glassy systems](#).