## Active dumbbells

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Work in collaboration with
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G. Gonnella, P. Di Gregorio, G.-L. Laghezza, A. Lamura, A. Mossa \& A. Suma (Bari \& Trieste, Italia, 2013-2015)

## Plan

## 5 lectures \& 2 exercise sessions

1. Introduction
2. Active Brownian dumbbells
3. Effective temperatures
4. Two-dimensional equilibrium phases
5. Two-dimensional collective behaviour of active systems

Third lecture

## Plan

## 5 lectures \& 2 exercise sessions

1. Introduction
2. Active Brownian dumbbells
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4. Two-dimensional equilibrium phases
5. Two-dimensional collective behaviour of active systems

## Plan

## 3rd Lecture

1. General discussion
2. Single active dumbbell
3. Collective active dumbbells
4. Interacting polymers with adamant motors
5. Experiments
6. Discussion

## Plan

## 3rd Lecture

## 1. General discussion

2. Single active dumbbell
3. Collective active dumbbells
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## An active bath



Dynamics of an open system
The system: the Brownian particle
A double bath: bacteria suspension
Interaction
‘Canonical setting'

A few Brownian particles or tracers • imbedded in an active bath
"Particle Diffusion in a Quasi-Two-Dimensional Bacterial Bath"
Wu \& Libchaber, Phys. Rev. Lett. 84, 3017 (2000)

## An active bath

## Enhanced motility



Mean-square displacement of the Brownian particle crossover form super-diffusion to diffusion
enhanced diffusion constant:
effective temperature
$t_{I}=m / \gamma \simeq 10^{-5} s$ and the first ballistic regime is not visible.
$D_{\text {eff }} \propto T_{\text {eff }}$ increases with $\phi$ and corresponds to $T_{\text {eff }} \simeq 100 T$
"Particle Diffusion in a Quasi-Two-Dimensional Bacterial Bath"
Wu \& Libchaber, Phys. Rev. Lett. 84, 3017 (2000)

## In and out of equilibrium

Take a mechanical point of view and call $\left\{\zeta_{i}\right\}(t)$ the variables e.g. particles' coordinates $\left\{\boldsymbol{r}_{i}(t)\right\}$ and velocities $\left\{\boldsymbol{v}_{i}(t)\right\}$

Choose an initial condition $\left\{\zeta_{i}\right\}(0)$ and let the system evolve.


- For $t_{w}>t_{e q}:\left\{\zeta_{i}\right\}(t)$ reach the equilibrium pdf and thermodynamics and statistical mechanics apply. Temperature is a well-defined concept.
- For $t_{w}<t_{e q}$ : the system remains out of equilibrium and thermodynamics and (Boltzmann) statistical mechanics do not apply.


## In and out of equilibrium

## Non-potential forces

Let $\left\{\zeta_{i}\right\}(t)$ be the positions of the (possibly interacting) particles.
Apply external forces that do not derive from a potential, $\boldsymbol{f}_{i} \neq-\nabla_{i} V(\{\boldsymbol{r}\})$ :
energy injection into the system.
Let the system evolve under $\boldsymbol{f}_{i}$ from $\left\{\boldsymbol{\zeta}_{i}\right\}(0)$


- Typically, for $t_{w}>t_{\mathrm{st}}:\left\{\boldsymbol{\zeta}_{i}\right\}(t)$ reach a non-equilibrium steady state in which thermodynamics and (Boltzmann) statistical mechanics do not obviously apply.

Is there a quantity to be associated to a temperature?

## Some basic properties

## requested

Control of heat-flows : $\Delta Q$ follows $\Delta T$.
Partial equilibration - transitivity :
$T_{A}=T_{B}, T_{B}=T_{C} \Rightarrow T_{A}=T_{C}$.
Measurable :
thermometers for systems in
good thermal contact ( $\Delta Q$ )


## Kinetic temperature

## First temptation

Associate a kinetic temperature $T_{\text {kin }}$ to the kinetic energy via

$$
k_{B} T_{\mathrm{kin}}\left(t_{0}\right)=m\left[\left\langle v_{a}^{2}\left(t_{0}\right)\right\rangle\right]
$$

equipartition. This is an instantaneous measurement. But, we know that

- the behaviour of the system depends on the time-delay at which we measure (recall e.g. the various regimes of the c.o.m. displacement

$$
\Delta_{\mathrm{cm}}\left(t+t_{0}, t_{0}\right)
$$

- in glasses the kinetic temperature is not a good measurement of out of equilibrium behaviour,


## Two-time observables

## Correlations


$t_{w}$ not necessarily longer than $t_{\text {eq }}$. Note change in names given to times (notation)

The two-time correlation between $A[\boldsymbol{\zeta}(t)]$ and $B\left[\boldsymbol{\zeta}\left(t_{w}\right)\right]$ is

$$
C_{A B}\left(t, t_{w}\right) \equiv\left\langle A[\boldsymbol{\zeta}(t)] B\left[\boldsymbol{\zeta}\left(t_{w}\right)\right]\right\rangle
$$

average over realizations of the dynamics (initial conditions, random numbers in a MC simulation, thermal noise in Langevin dynamics, etc.)

## Two-time observables

## Linear response



The perturbation couples linearly to the observable $B\left[\boldsymbol{\zeta}\left(t_{w}\right)\right]$

$$
E \rightarrow E-h B\left[\boldsymbol{\zeta}\left(t_{w}\right)\right]
$$

The linear instantaneous response of another observable $A[\boldsymbol{\zeta}(t)]$ is

$$
\left.R_{A B}\left(t, t_{w}\right) \equiv \frac{\delta\langle A[\boldsymbol{\zeta}(t)]\rangle_{h}}{\delta h\left(t_{w}\right)}\right|_{h=0}
$$

The linear integrated response is

$$
\chi_{A B}\left(t, t_{w}\right) \equiv \int_{t_{w}}^{t} d t^{\prime} R_{A B}\left(t, t^{\prime}\right)
$$



Rue de Fossés St. Jacques et rue St. Jacques
Paris 5ème Arrondissement.

## Fluctuation-dissipation

## In thermal equilibrium

$$
P\left(\boldsymbol{\zeta}, t_{w}\right)=P_{\mathrm{eq}}(\boldsymbol{\zeta})
$$

- The dynamics are stationary

$$
C_{A B} \rightarrow C_{A B}\left(t-t_{w}\right) \text { and } R_{A B} \rightarrow R_{A B}\left(t-t_{w}\right)
$$

The fluctuation-dissipation theorem between spontaneous $\left(C_{A B}\right)$ and induced $\left(R_{A B}\right)$ fluctuations

$$
R_{A B}\left(t-t_{w}\right)=-\frac{1}{k_{B} T} \frac{\partial C_{A B}\left(t-t_{w}\right)}{\partial t} \theta\left(t-t_{w}\right)
$$

holds and implies

$$
\chi_{A B}\left(t-t_{w}\right) \equiv \int_{t_{w}}^{t} d t^{\prime} R_{A B}\left(t, t^{\prime}\right)=\frac{1}{k_{B} T}\left[C_{A B}(0)-C_{A B}\left(t-t_{w}\right)\right]
$$

## Fluctuation-dissipation

## Linear relation between $\chi$ and $C$

$$
P\left(\boldsymbol{\zeta}, t_{w}\right)=P_{\mathrm{eq}}(\boldsymbol{\zeta})
$$

The dynamics are stationary

$$
C_{A B} \rightarrow C_{A B}\left(t-t_{w}\right) \text { and } R_{A B} \rightarrow R_{A B}\left(t-t_{w}\right)
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holds and implies

$$
\chi_{A B}\left(t-t_{w}\right) \equiv \int_{t_{w}}^{t} d t^{\prime} R_{A B}\left(t, t^{\prime}\right)=\frac{1}{k_{B} T}\left[C_{A B}(0)-C_{A B}\left(t-t_{w}\right)\right]
$$

## Fluctuation-dissipation

Linear relation between $\chi$ and $\Delta$

$$
P\left(\boldsymbol{\zeta}, t_{w}\right)=P_{\mathrm{eq}}(\boldsymbol{\zeta})
$$

The dynamics are stationary

$$
\begin{aligned}
\Delta_{A B}\left(t, t_{w}\right) & =\left\langle\left[A(t)-B\left(t_{w}\right)\right]^{2}\right\rangle=2\left[C_{A A}(0)+C_{B B}(0)-C_{A B}\left(t-t_{w}\right)\right] \\
& \rightarrow \Delta_{A B}\left(t-t_{w}\right)
\end{aligned}
$$

The fluctuation-dissipation theorem between spontaneous $\left(\Delta_{A B}\right)$ and induced $\left(R_{A B}\right)$ fluctuations

$$
R_{A B}\left(t-t_{w}\right)=\frac{1}{2 k_{B} T} \frac{\partial \Delta_{A B}\left(t-t_{w}\right)}{\partial t} \theta\left(t-t_{w}\right)
$$

holds and implies

$$
\chi_{A B}\left(t-t_{w}\right) \equiv \int_{t_{w}}^{t} d t^{\prime} R_{A B}\left(t, t^{\prime}\right)=\frac{1}{2 k_{B} T}\left[\Delta_{A B}\left(t-t_{w}\right)-\Delta_{A B}(0)\right]
$$

## Brownian motion



First example of dynamics of an open system
The system: the Brownian particle

The bath: the liquid
Interaction: collisional or potential
‘Canonical setting’

A few Brownian particles or tracers • imbedded in, say, a molecular liquid.
Late XIX, early XX (Brown, Einstein, Langevin)

## Fluctuation-dissipation

## Brownian motion

$$
m \dot{v}+\gamma v=h+\eta
$$



Correlation $\left\langle x(t) x\left(t_{w}\right)\right\rangle_{h=0} \mapsto 2 \frac{k_{B} T}{\gamma} \min \left(t, t_{w}\right)$ at $t, t_{w} \gg t_{I}$ Stationary Displacement $\left\langle\left[x(t)-x\left(t_{w}\right)\right]^{2}\right\rangle_{h=0} \mapsto 2 \frac{k_{B} T}{\gamma}\left(t-t_{w}\right)$ at $t, t_{w} \gg t_{I}$ Linear response $\left.\frac{\delta\langle x(t)\rangle_{h}}{\delta h\left(t_{w}\right)}\right|_{h=0}=\gamma^{-1} \theta\left(t-t_{w}\right)$

$$
2 k_{B} T R_{x x}\left(t, t_{w}\right)=\partial_{t_{w}} C_{x x}\left(t, t_{w}\right) \theta\left(t-t_{w}\right)
$$

FDT does not hold

$$
2 k_{B} T R_{x x}\left(t, t_{w}\right)=\partial_{t} \Delta_{x x}\left(t, t_{w}\right) \theta\left(t-t_{w}\right)
$$

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## Fluctuation-dissipation

## Active dumbbell in the last diffusive regime

The c.o.m. diffuses, $\Delta_{\mathrm{cm}}^{2}\left(t+t_{0}, t_{0}\right) \simeq 2 d D_{A} t$, for $t \gg t_{a}$, with the diffusion constant $D_{A}=k_{B} T /(2 \gamma)\left(1+\mathrm{Pe}^{2}\right)$

The c.o.m. integrated linear response function $\chi_{\mathrm{cm}}\left(t+t_{0}, t_{0}\right)=d \mu t$ with the mobility $\mu=1 /(2 \gamma)$

We use the deviation from equilibrium fluctuation-dissipation theorem,

$$
\chi_{\mathrm{cm}}\left(t+t_{0}, t_{0}\right)=2 k_{B} T_{\mathrm{eff}}\left(t+t_{0}, t_{0}\right) \Delta_{\mathrm{cm}}^{2}\left(t+t_{0}, t_{0}\right)
$$

to define, a possibly time(s)-dependent, effective temperature, $T_{\text {eff }}$.
For the active dumbbell, at $t>t_{a}$, we find a constant

$$
k_{B} T_{\mathrm{eff}}=\frac{\mu}{D_{A}}=k_{B} T\left(1+\frac{\mathrm{Pe}^{2}}{8}\right)
$$

## Fluctuation-dissipation

## Active dumbbell in the last diffusive regime

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The c.o.m. integrated linear response function $\chi_{\mathrm{cm}}\left(t+t_{0}, t_{0}\right)=d \mu t$ with the mobility $\mu=1 /(2 \gamma)$ implying

$$
k_{B} T_{\text {eff }}=\frac{\mu}{D_{A}}=k_{B} T\left(1+\frac{\mathrm{Pe}^{2}}{8}\right)
$$

Exercise: Prove these results.

## Fluctuation-dissipation

## Active dumbbell

The definition of the effective temperature using the deviation from the equilibrium fluctuation-dissipation theorem

$$
\chi_{\mathrm{cm}}\left(t+t_{0}, t_{0}\right)=2 k_{B} T_{\mathrm{eff}}\left(t+t_{0}, t_{0}\right) \Delta_{\mathrm{cm}}^{2}\left(t+t_{0}, t_{0}\right)
$$

is not equivalent to the kinetic temperature

$$
k_{B} T_{\mathrm{kin}}\left(t_{0}\right)=2 m_{\mathrm{d}}\left\langle v_{\mathrm{cm} a}^{2}\left(t_{0}\right)\right\rangle
$$

- The kinetic temperature concerns the velocity variable while the effective temperature concerns the position variable.
- The kinetic temperature is an instantaneous measurement while the effective temperature is a time-delayed measurement.


## Fluctuation-dissipation

## Active dumbbell

The definition of the effective temperature using the deviation from the equilibrium fluctuation-dissipation theorem yields

$$
k_{B} T_{\text {eff }}=k_{B} T\left(1+\mathrm{Pe}^{2} / 8\right)
$$

and is not equivalent to the kinetic temperature

$$
k_{B} T_{\text {kin }}=k_{B} T\left[1+m_{\mathrm{d}} k_{B} T /\left(2 \gamma \sigma_{\mathrm{d}}\right)^{2} \mathrm{Pe}^{2}\right]
$$

- The kinetic temperature concerns the velocity variable while the effective temperature concerns the position variable.
- The kinetic temperature is an instantaneous measurement while the effective temperature is a time-delayed measurement.


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## Fluctuation-dissipation

## Active finite (low) density dumbbell system

$$
\phi=0.1
$$




## Fluctuation-dissipation

$$
\chi_{\mathrm{cm}}\left(t+t_{0}, t_{0}\right)=2 k_{B} T_{\mathrm{eff}} \Delta_{\mathrm{cm}}^{2}\left(t+t_{0}, t_{0}\right)
$$



$$
T=0.05
$$

$$
\mathrm{Pe} \simeq 4 \quad \mathrm{Pe} \simeq 40
$$

Very weak $\phi$-dependence in this scale but...

## Fluctuation-dissipation

$$
\chi_{\mathrm{cm}}\left(t+t_{0}, t_{0}\right)=2 k_{B} T_{\mathrm{eff}} \Delta_{\mathrm{cm}}^{2}\left(t+t_{0}, t_{0}\right)
$$

Non monotonic dependence on $\phi$

"Dynamics of a homogeneous active dumbbell system", Suma, Gonnella, Laghezza, Lamura, Mossa \& LFC, Phys. Rev. E 90, 052130 (2014)

## Fluctuation-dissipation

$$
\chi_{\mathrm{cm}}\left(t+t_{0}, t_{0}\right)=2 k_{B} T_{\mathrm{eff}} \Delta_{\mathrm{cm}}^{2}\left(t+t_{0}, t_{0}\right)
$$


"Dynamics of a homogeneous active dumbbell system", Suma, Gonnella, Laghezza, Lamura, Mossa \& LFC, Phys. Rev. E 90, 052130 (2014)

## Effective temperature

## Properties and measurement

- Relation to entropy.
- Control of heat-flows : $\Delta Q$ follows $\Delta T$.
- Partial equilibration - transitivity :

$$
T_{A}=T_{B}, T_{B}=T_{C} \Rightarrow T_{A}=T_{C}
$$

thermometers for systems in
good thermal contact ( $\Delta Q$ )
Review LFC 11


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## Interacting polymers

The "DNA" example


> Molecular dynamics
> Linear molecules
> $\mathbf{F}_{i}^{\text {det }}$ deterministic force
> $\mathbf{F}_{i}^{\text {act }}$ stochastic motor forces
> act during $\tau$

$$
m \dot{\boldsymbol{v}}_{i}+\gamma \boldsymbol{v}_{i}=\mathbf{F}_{i}^{\operatorname{det}}\left(\left\{\boldsymbol{r}_{j}\right\}\right)+\mathbf{F}_{i}^{\text {act }}+\boldsymbol{\eta}_{i}
$$

## Interacting polymers

## The "DNA" example



Molecular dynamics<br>Linear molecules<br>$\mathbf{F}_{i a}^{\text {det }}$ deterministic force<br>$\mathbf{F}_{i a}^{\text {act }}$ stochastic motor forces<br>act during $\tau$<br>on \% polymers<br>Passive tracers

$$
m \dot{\boldsymbol{v}}_{i a}+\gamma \boldsymbol{v}_{i a}=\mathbf{F}_{i a}^{\mathrm{det}}\left(\left\{\boldsymbol{r}_{j}\right\}\right)+\mathbf{F}_{i a}^{\text {act }}+\boldsymbol{\eta}_{i a}
$$

Loi, Mossa \& LFC 08-11

## Interacting polymers

## Forces

$$
\mathbf{F}_{\alpha i}^{\mathrm{det}}=-\sum_{\nu(\neq \alpha)}^{N_{p}} \sum_{j=1}^{N_{m}} \nabla_{\nu j} V_{\mathrm{inter}}\left(r_{\alpha i \nu j}\right)-\sum_{j=1}^{N_{m}} \nabla_{\nu j} V_{\mathrm{intra}}\left(r_{\alpha i \nu j}\right)
$$

mechanical force acting on monomer $i$ in polymer $\alpha$ exerted by the other monomers in the same and different polymers.

The inter and intra polymer potentials are of Lennard-Jones type :

$$
\begin{aligned}
& V_{\text {inter }}(r)=\left\{4 \epsilon\left[\left(\frac{\sigma}{r}\right)^{12}-\left(\frac{\sigma}{r}\right)^{6}\right]+\epsilon\right\} \theta\left(2^{1 / 6} \sigma-r\right) \\
& V_{\text {intra }}(r)= \begin{cases}k\left(r-r_{0}\right)^{2} & \mathrm{nn} \\
\left\{4 \epsilon\left[\left(\frac{S}{r}\right)^{12}-\left(\frac{S}{r}\right)^{6}\right]+\epsilon\right\} \theta\left(2^{1 / 6} \sigma-r\right) & \text { next nn }\end{cases}
\end{aligned}
$$

Unit of energy, $2 k_{B} T$, length 0.4 nm , force 20 pN at ambient temperature.

## Interacting polymers

## Structure of the passive model : liquid

Parameters such that lines are semi-flexible $S=2.5 r_{0}$ in liquid phase
Miura et al., Phys. Rev. E 63, 061807 (2001).
For $N_{p}=250$ and $\rho=1, N_{m}$-independent structure factor for $N_{m} \gtrsim 21$.


1st peak
$q_{0}^{-1} \simeq \mathrm{nn}$ distance (typically $\alpha \neq \nu$ )
2nd peak
$q_{1}^{-1} \simeq$ equil. bond $r_{0}$

Analysis of radius of gyration : non-Gaussian chains.

## Interacting polymers

## Dynamics of the passive model : liquid



$$
\begin{aligned}
& D \simeq N_{m}^{-1} \\
& \tau_{\alpha} \simeq N_{m}^{3 / 4} \\
& \text { for } \\
& N_{m} \lesssim 50
\end{aligned}
$$

We used

$$
N_{m}=21
$$

$$
\begin{array}{ll}
\left.\Delta^{2}(t)=\frac{1}{N_{p} N_{m}} \sum_{\alpha=1}^{N_{p}} \sum_{i=1}^{N_{m}}\langle | r_{\alpha i}\left(t+t_{0}\right)-\left.r_{\alpha i}\left(t_{0}\right)\right|^{2}\right\rangle & \text { Mean-square displacement } \\
F_{s}(\boldsymbol{Q}, t)=\frac{1}{N_{p} N_{m}} \sum_{\alpha=1}^{N_{p}} \sum_{i=1}^{N_{m}}\left\langle e^{\left.i \boldsymbol{Q}\left[r_{\alpha i}\left(t+t_{0}\right)-r_{\alpha i}\left(t_{0}\right)\right]\right\rangle}\right\rangle & \text { Incoherent scattering }
\end{array}
$$

## Interacting polymers

## Adamant motor activity

Requirements :

- Homogeneously distributed in the sample.
- Motor acts at the center of the polymers (OK on short time-scales).
- Linear response regime.

Intensity given by a fraction of the conservative mechanical force of the passive system

$$
\left|\mathbf{F}_{\alpha i}^{\text {act }}\right|=f \frac{1}{N_{p} N_{m}} \sum_{\alpha=1}^{N_{p}} \sum_{i=1}^{N_{m}}\left|\mathbf{F}_{\alpha i}^{\text {det }}\right|=f \bar{F} \quad \bar{F} \simeq 163.5
$$

- Time series of randomly applied kicks on \% polymers.
- Activation time scale $\tau=500$ MDs: constant $\mathbf{F}_{\alpha i}^{\text {act }}$ over this period.

The motor action is independent of the structural rearrangements induced

## Interacting polymers

## Structure properties



1st peak $\rightarrow$ right :
nn dist. decreases, i.e. crowding.

Width increases \& height decreases, i.e. disorder.

Averaged radius of gyration decreases with increasing $f$ : chain folding.
Complex dependence of its pdf with $f$.

## Interacting polymers

## Dynamics: the diffusion constant increases with Pe



$$
D_{A} / D \simeq 1+1423 f^{2.29}
$$



$$
\left(\tau_{A} / \tau\right)^{-1} \simeq 1+19 f
$$

Could the exponent be actually 2 and $D_{A} / D \simeq 1+c \mathrm{Pe}^{2}$ as for the dumbbell system

## Active matter

## Integrated linear response against correlation function


$q_{0}$ first peak in structure factor

$$
\begin{aligned}
& C(t) \propto \sum\left\langle e^{i \boldsymbol{q}_{0} \cdot\left[\boldsymbol{r}\left(t+t_{0}, t_{0}\right)-\boldsymbol{r}\left(t_{0}\right)\right]}\right\rangle \\
& \left.\chi(t) \propto \sum \int_{t_{0}}^{t+t_{0}} d t^{\prime} \frac{\delta\left\langle e^{i \boldsymbol{q}_{0} \cdot \boldsymbol{r}\left(t+t_{0}\right)}\right\rangle}{\delta h\left(t^{\prime}\right)}\right|_{h=0} \\
& H \rightarrow H-2 h \sum \epsilon \cos \left(\boldsymbol{q}_{0} \cdot \boldsymbol{r}\right)
\end{aligned}
$$

Sums over all monomers, $t$ is time-delay

$$
\chi(t)=\frac{1}{k_{B} T_{\mathrm{eff}}(t)}[C(0)-C(t)]
$$

In equilibrium $T_{\text {eff }}(t)=T$. Here, $T_{\text {eff }}(f)=c t>T$, for small $C$.

## Interacting polymers

## Tracer's velocities

Spherical particles with mass $m_{\mathrm{tr}}$ that interact with the active matter.


Maxwell pdf of tracers' velocities $v$ at an effective temperature $T_{\text {eff }}\left(m_{\text {tr }}\right)$.

## Interacting polymers

## Tracer's diffusion (cfr. Wu \& Libchaber's work)




$$
\Delta_{\mathrm{tr}}^{2}\left(t+t_{0}, t_{0}\right)=\left\langle\left[\boldsymbol{r}\left(t+t_{0}\right)-\boldsymbol{r}\left(t_{0}\right)\right]^{2}\right\rangle \simeq 2 d D t
$$

Brownian motion : $D \propto k_{B} T \quad$ in active matter

$$
D_{\text {eff }} \propto k_{B} T_{\text {eff }}
$$

## Interacting polymers

Outcome of FDT on polymers \& tracers' diffusion and kinetic energy


$$
T_{\mathrm{eff}} / T \simeq 1+c f^{2} \quad \stackrel{?}{=} 1+c \mathrm{Pe}^{2}
$$

$c \simeq 15.41$ for filaments and $c \simeq 1.18$ for particles.

## Partial equilibrations

## Wave-vector dependence analysis



Lennard-Jones binary mixture
Berthier \& Barrat 00
Fine


Active disks
Levis \& Berthier 15
Problems

To be further studied

## Experiments

## Human FDT


"Human Balance out of Equil. : Nonequilibrium Statistical Mechanics in Posture Control", Lauk, Chow, Pavlik \& Collins, Phys. Rev. Lett. 80, 413 (1998)

## Experiments

Ear Hair bundle

"Comparison of a hair bundle's spontaneous oscillations with its response to mechanical stimulation reveals the underlying active process"

Martin, Hudspeth \& Jülicher, PNAS 98, 14380 (2001)

## Experiments

## Mechanical response of the cell cytoskeleton



"Non equilibrium mechanics of active cytoskeletal network"
Mizuno, Tardin, Schmidt, MacKintosh, Science 315, 370 (2015)

## Experiments

## Boltzmann distribution for the sedimentation of a gas

Under the only effect of gravity, how does the density of a perfect gas depend upon the vertical distance $z$ from a reference $z_{0}$ ?

$$
P(z+d z)-P(z)=-m g \rho(z) d z \quad \Rightarrow \quad \frac{d P(z)}{d z}=m g \rho(z)
$$

with $m$ the mass of the particles in the gas, $g$ the gravitational acceleration, $\rho(z)$ the density of the gas at height $z$ and $P(z)$ its pressure at the same height.

Using the perfect gas law $P(z)=\rho(z) k_{B} T$

$$
\frac{d \rho(z)}{d z}=-\frac{m g}{k_{B} T} \rho(z) \Rightarrow \rho(z)=\rho\left(z_{0}\right) e^{-\beta m g z}
$$

## Experiments

Sedimentation of Janus particles in a very dilute limit



$$
\rho(z) \simeq \rho_{0} e^{-z / \delta_{\mathrm{eff}}} \text { with } \delta_{\mathrm{eff}}=\frac{k_{B} T_{\mathrm{eff}}}{m g} \propto D_{\mathrm{eff}}
$$

"Sedimentation and effective temperature of active colloidal suspensions"
Palacci et al. Phys. Rev. Lett. 105, 088304 (2010)

## Summary

- Deviations from FDT reveal the nonequilibrium character of a system.
- It was used for ear hair bundles, the cytoskeleton, bacterial baths, etc.

A time-delay dependent effective temperature can be extracted from the modification of the FDT.

- Its thermodynamic properties have to be tested by measuring it with thermometers, checking partial equilibrations, etc.
- In low density interacting systems of particles and polymers under adamant motors (homogeneous liquid systems)
- In interacting active dumbbell systems : need to revisit the effects of clustering and coexistence (see next lectures!)
- In active hard disk models : same claim as above.
- In Vicsek model : + difficulty posed by singular passive limit.

